Anderson Localization and the Space-Time Characteristic of Continuum States

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A proof of Anderson localization is obtained by ruling out any continuous spectrum on the basis of the space-time characteristic of its states.

KEY WORDS: Anderson localization.

1. INTRODUCTION AND RESULTS

By now many $proofs^{(1,4,5,11)}$ of localization for the *d*-dimensional Anderson model have been given. Common to all of them, as to this one, is the derivation of some form of exponential decay⁽⁸⁾ of the Green's function. In a second step, localization, i.e., absence of continuous spectrum, is then obtained either^(1,4,11) using results about the behavior of the spectral measure under rank-one perturbations, or^(4,5,7) using that the set of generalized eigenvalues has full spectral measure. The purpose of this paper is to show that this step can be done using a characterization of the continuous spectrum due to Ruelle⁽¹⁰⁾ and Amrein and Georgescu.^(2,6) Such a possibility has been conjectured in ref. 8. For the one-dimensional model it has been used in refs. 3 and 9.

We consider just the simplest case. This is the discrete Schrödinger operator

$$h_{\omega} = -\Delta + v_{\omega}$$

acting on $l^2(\mathbb{Z}^d)$, where Δ is the discrete Laplacian

$$(\varDelta \psi)(x) = \sum_{|e| = 1} \psi(x+e)$$

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and v_{ω} is a random potential

$$(v_{\omega}\psi)(x) = v_{x}\psi(x)$$

Here $|x| = \sum_{i=1}^{d} |x_i|$ and $\omega = \{v_x\}_{x \in \mathbb{Z}^d}$ is a collection of independent identically distributed random variables. We shall assume that the single-site probability distribution has a density $\rho \in L^1(\mathbb{R})$, $\|\rho\|_1 = 1$, with respect to Lebesgue measure. In other words, the probability space $\Omega = X_{x \in \mathbb{Z}^d} \mathbb{R}$ is equipped with the probability measure $dP(\omega) = \prod_{x \in \mathbb{Z}^d} \rho(v_x) dv_x$.

The strength of the disorder is measured by $\|\rho\|_{\infty}^{-1}$. Localization occurs if the disorder is large enough.

Theorem 1. Let $\rho \in L^{\infty}(\mathbb{R})$ and of compact support. If $\|\rho\|_{\infty}$ is small enough, then h_{ω} has only pure point spectrum with probability 1.

Ruelle's criterion asserts that states associated with the continuous spectrum leave any compact set in the time mean. More precisely, let E_c be the projection onto the continuous spectral subspace of an operator h on $l^2(\mathbb{Z}^d)$ and let $P_{|x| \ge R}$ be the projection onto wave functions which vanish in $\{x \in \mathbb{Z}^d \mid |x| < R\}$. Then

$$\|E_{\varepsilon}\psi\|^{2} = \lim_{R \to \infty} \lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} ds \|P_{|x| \ge R} e^{-ihs}\psi\|^{2}$$
(1)
$$= \lim_{R \to \infty} \lim_{\varepsilon \downarrow 0} 2\varepsilon \int_{0}^{\infty} ds \ e^{-2\varepsilon s} \|P_{|x| \ge R} e^{-ihs}\psi\|^{2}$$
$$= \lim_{R \to \infty} \lim_{\varepsilon \downarrow 0} \frac{\varepsilon}{\pi} \int dE \|P_{|x| \ge R} (h - E - i\varepsilon)^{-1} \psi\|^{2}$$
(2)

The Green's function consists of matrix elements of the resolvent

$$G(x, y; z) = (\delta_x, (h-z)^{-1} \delta_y)$$

where the states δ_n are given by $\delta_n(m) = \delta_{nm}$ $(n, m \in \mathbb{Z}^d)$.

Lemma 2. Let $\|\rho\|_{\infty}$ be small enough and 0 < s < 1. Then there are C, m > 0 such that

$$\langle |G_{\omega}(x, y; z)|^{s} \rangle \leq C e^{-m|x-y|} \tag{3}$$

for all $z \in \mathbb{C} \setminus \mathbb{R}$, $x, y \in \mathbb{Z}^d$.

Here $\langle \cdot \rangle$ denotes the expectation with respect to the probability measure. In ref. 1 a similar estimate was obtained. There the Green's function is regularized by going to finite volumes; here, by going to complex energies.

We then extend the result to higher moments of the Green's function. Specifically:

Lemma 3. Let ρ be as in Lemma 2 and, in addition, of compact support. Then there are C, m > 0 such that

$$|\operatorname{Im} z| \langle |G_{\omega}(x, y; z)|^2 \rangle \leq C e^{-m|x-y|}$$
(4)

for all $z \in \mathbb{C} \setminus \mathbb{R}$, $x, y \in \mathbb{Z}^d$.

Note that the moment of the Green's function in (3) stays bounded as z approaches the real axis, whereas in (4) it may diverge like $|\text{Im } z|^{-1}$. Setting $z = E + i\varepsilon$, we shall see that (4) controls the expectation of (2).

The conductivity tensor as defined by the Kubo–Greenwood formula⁽⁸⁾ is

$$\sigma_{ij}(E) = \lim_{\epsilon \downarrow 0} \frac{\varepsilon^2}{\pi} \sum_{x \in \mathbb{Z}^d} x_i x_j \langle |G_{\omega}(0, x; E + i\varepsilon)|^2 \rangle$$

From (4) we immediately get:

Corollary 4:

$$\sigma_{ii}(E) = 0$$

2. PROOFS

We follow ref. 1 quite closely and begin with:

Lemma 5. Let 0 < s < 1. Then there is C > 0 such that

$$\langle |G_{\omega}(x, y; z)|^{s} \rangle \leq C \|\rho\|_{\infty}^{s}$$
⁽⁵⁾

for all $z \in \mathbb{C} \setminus \mathbb{R}$, $x, y \in \mathbb{Z}^d$.

Proof. We assume $x \neq y$, the case x = y being similar but easier. The dependence of $G_{\omega}(x, y; z)$ on v_x , v_y (at fixed values of the potential elsewhere) is particularly simple. To exhibit it, one writes

$$h_{\alpha} = h_{\dot{\alpha}} + v_x P_x + v_y P_y$$

where $\hat{\omega}$ is obtained from ω by setting $v_x = v_y = 0$, and $P_n = \delta_n(\delta_n, \cdot)$ are the projections on the states δ_n . Note that h_{ω} differs from $h_{\hat{\omega}}$ by a rank-2 perturbation acting on the range of $P = P_x + P_y$. From the second resolvent identity $(h_{\hat{\omega}} - z)^{-1} = [1 + (h_{\hat{\omega}} - z)^{-1} (v_x P_x + v_y P_y)](h_{\omega} - z)^{-1}$ we obtain an identity on Ran P known as Krein's formula:

$$P(h_{\omega} - z)^{-1} P = (A + v_{x}P_{x} + v_{y}P_{y})^{-1}$$
(6)

where $A = [P(h_{\dot{\omega}} - z)^{-1} P]^{-1}$, provided it exists, acts on Ran P and is independent of v_x , v_y . It indeed exists for $z \in \mathbb{C} \setminus \mathbb{R}$ because $(\text{Im } z)^{-1}$ $\text{Im}(h_{\dot{\omega}} - z)^{-1} = (h_{\dot{\omega}} - \bar{z})^{-1} (h_{\dot{\omega}} - z)^{-1}$ is positive definite. In particular,

$$-\frac{\text{Im }A}{\text{Im }z} = \frac{1}{\text{Im }z} \frac{A^* - A}{2i} = A^* P \frac{\text{Im}(h_{\dot{\omega}} - z)^{-1}}{\text{Im }z} PA$$

is positive definite, too. Using matrix notation with respect to the basis $\{\delta_x, \delta_y\}$,

$$A = \begin{pmatrix} a_{xx} & a_{xy} \\ a_{yx} & a_{yy} \end{pmatrix}, \quad \text{Im } A = \begin{pmatrix} \text{Im } a_{xx} & (1/2i)(a_{xy} - \overline{a}_{yx}) \\ (1/2i)(a_{yx} - \overline{a}_{xy}) & \text{Im } a_{yy} \end{pmatrix}$$

we thus have from (6)

$$G_{\omega}(x, y; z) = -\frac{a_{xy}}{(v_x + a_{xx})(v_y + a_{yy}) - a_{xy}a_{yx}}$$
(7)

By retaining only the real, resp. the imaginary part of the denominator, we get

$$|G_{\omega}(x, y; z)| \leq \frac{|a_{xy}|}{|u_x u_y - \operatorname{Im} a_{xx} \operatorname{Im} a_{yy} - \operatorname{Re}(a_{xy} a_{yx})|}$$
$$|G_{\omega}(x, y; z)| \leq \frac{|a_{xy}|}{|u_x \operatorname{Im} a_{yy} + u_y \operatorname{Im} a_{xx} - \operatorname{Im}(a_{xy} a_{yx})|}$$

with $u_i = v_i + \operatorname{Re} a_{ii}$ (i = x, y). Moreover,

det Im
$$A = \text{Im } a_{xx} \text{ Im } a_{yy} + \frac{1}{2} \text{Re}(a_{xy}a_{yx}) - \frac{1}{4}(|a_{xy}|^2 + |a_{yx}|^2) > 0$$
 (8)

(i) We shall first treat the case where

$$\max(|\text{Im } a_{xx}|, |\text{Im } a_{yy}|) < \frac{1}{2}|a_{xy}|$$
(9)

Using (8), we then have

$$c^{2} := \operatorname{Im} a_{xx} \operatorname{Im} a_{yy} + \operatorname{Re}(a_{xy}a_{yx})$$

> $\frac{1}{2}(|a_{xy}|^{2} + |a_{yx}|^{2}) - \operatorname{Im} a_{xx} \operatorname{Im} a_{yy} > \frac{1}{4}|a_{xy}|^{2}$

and thus

$$|G_{\omega}(x, y; z)| \leq \frac{2c}{|u_{x}u_{y} - c^{2}|} = \frac{2c^{-1}}{|c^{-2}u_{x}u_{y} - 1|}$$

We note that for any $w_x, w_y \in \mathbb{R}$

$$\min(|w_x - f(w_y)|, |w_y - f(w_x)|) \le |w_x w_y - 1|$$
(10)

where $wf(w) = \min(1, w^2)$. Indeed, if $w_x^2 \ge 1$, then

$$|w_y - f(w_x)| = |w_y - w_x^{-1}| \le |w_x w_y - 1|$$

and the same argument applies if $w_y^2 \ge 1$. If, however, w_x^2 , $w_y^2 < 1$, then

$$[w_x - f(w_y)]^2 = [w_y - f(w_x)]^2 = (w_x - w_y)^2$$

= $(w_x w_y - 1)^2 - (1 - w_x^2)(1 - w_y^2) < (w_x w_y - 1)^2$

By (10) we estimate

$$|G_{\omega}(x, y; z)|^{s} \leq 2^{s} (|u_{x} - cf(c^{-1}u_{y})|^{-s} + |u_{y} - cf(c^{-1}u_{x})|^{-s})$$

To estimate its expectation we shall use that

$$\int dv \,\rho(v) \,|v-\beta|^{-s} \leq \lambda^{-s} \int_{|v-\beta| \geq \lambda} dv \,\rho(v) + \|\rho\|_{\infty} \int_{|v-\beta| < \lambda} dv \,|v-\beta|^{-s}$$
$$\leq \lambda^{-s} \,\|\rho\|_{1} + \frac{2\lambda^{1-s}}{1-s} \,\|\rho\|_{\infty} \leq C_{s} \,\|\rho\|_{1}^{1-s} \,\|\rho\|_{\infty}^{s} \tag{11}$$

with $C_s = (2/s)^s (1-s)^{-1}$ after minimizing over $\lambda > 0$. (This estimate holds for any $\beta \in \mathbb{C}$ although we use it here for $\beta \in \mathbb{R}$). Hence

$$\int dv_x \, dv_y \, \rho(v_x) \, \rho(v_y) \, |G_{\omega}(x, y; z)|^s \leq 2 \cdot 2^s C_s \, \|\rho\|_{\infty}^s$$

(ii) In case (9) fails, we have $|\text{Im } a_{ii}| \ge |a_{xy}|/2$ for i = x or i = y. We shall consider only i = y, the other case being similar. Then

$$|G_{\omega}(x, y; z)| \leq \frac{2}{|u_x + [u_y \operatorname{Im} a_{xx} - \operatorname{Im}(a_{xy}a_{yx})](\operatorname{Im} a_{yy})^{-1}|} \int dv_x \, dv_y \, \rho(v_x) \, \rho(v_y) \, |G_{\omega}(x, y; z)|^s \leq 2^s C_s \, \|\rho\|_{\infty}^s$$

By joining the results of the two cases, we see that the expectation with respect to v_x , v_y is bounded uniformly in $\hat{\omega}$.

Similarly, the next tool is a version of the decoupling lemma of ref. 1. Lemma 6. Let 0 < s < 1. Then there is c > 0 such that

$$\frac{\int dv \,\rho(v)(|v-\eta|^{s}/|v-\beta|^{s})}{\int dv \,\rho(v)(1/|v-\beta|^{s})} \ge c \,\frac{\|\rho\|_{1}^{s}}{\|\rho\|_{\infty}^{s}}$$
(12)

for all $\rho \in L^1(\mathbb{R}) \cap L^{\infty}(\mathbb{R})$, $0 \not\equiv \rho \ge 0$, and all β , $\eta \in \mathbb{C}$.

Proof. We may assume $\eta \in \mathbb{R}$ since the integral in the numerator becomes smaller upon replacing η by its real part. By translation we may then assume $\eta = 0$. Finally, by scaling we may assume $\|\rho\|_1 = \|\rho\|_{\infty} = 1$. We then write N (resp. D) for the numerator (resp. denominator) of the fraction in (12) and distinguish between the cases (i) $\int_{\|v\| \ge |\beta|} dv \rho(v) \ge 1/2$ and (ii) $\int_{\|v\| \le |\beta|} dv \rho(v) > 1/2$.

(i) In this case,

$$N \ge \int_{|v| \ge |\beta|} dv \,\rho(v) \frac{|v|^s}{|v-\beta|^s} \ge 2^{-s} \int_{|v| \ge |\beta|} dv \,\rho(v) \ge 2^{-(s+1)}$$

and $D \leq C_s$ by (11).

(ii) For any $\lambda > 0$

$$\int_{|v| \leq \lambda} dv \,\rho(v) \,\frac{1}{|v-\beta|^s} \leq \int_{|v| \leq \lambda} dv \,\frac{1}{|v-\beta|^s} \leq \min\left(\frac{2\lambda}{(|\beta|-\lambda)_+^s}, \frac{2\lambda^{1-s}}{1-s}\right) \leq \operatorname{const} \cdot \lambda \,|\beta|^{-s}$$

so that

$$N \ge \lambda^s \int_{|v| > \lambda} dv \, \rho(v) \frac{1}{|v - \beta|^s} \ge \lambda^s (D - \operatorname{const} \cdot \lambda |\beta|^{-s})$$

Since

$$D \ge \int_{|v| < |\beta|} dv \,\rho(v) \,\frac{1}{|v - \beta|^s} \ge (2 \,|\beta|)^{-s} \int_{|v| < |\beta|} dv \,\rho(v) > \frac{1}{2} \,(2 \,|\beta|)^{-s}$$

we find $N/D \ge \lambda^s(1-c\lambda) \ge \text{const}$ for some constant c and $\lambda = (2c)^{-1}$.

Proof of Lemma 2.⁽¹⁾ According to (7), we have

$$G_{\omega}(x, y; z) = \frac{\alpha}{v_{y} - \beta}$$
(13)

where α , β depend on $\{v_i\}_{i \neq y}$, but not on v_y . By taking the xy matrix element of $(h_{\omega} - z)^{-1} (h_{\omega} - z) = \mathbb{I}$, we obtain for $y \neq x$

$$\sum_{|e|=1} G_{\omega}(x, y+e; z) = (v_y - z) G_{\omega}(x, y; z)$$

and hence

$$\sum_{|e|=1} |G_{\omega}(x, y+e; z)|^{s} \ge |v_{y}-z|^{s} |G_{\omega}(x, y; z)|^{s}$$

We then take expectations using (13), (12),

$$\left\langle \sum_{|e|=1} |G_{\omega}(x, y+e; z)|^{s} \right\rangle \ge \left\langle |v_{y}-z|^{s} |G_{\omega}(x, y; z)|^{s} \right\rangle$$
$$\ge c \|\rho\|_{\infty}^{-s} \left\langle |G_{\omega}(x, y; z)|^{s} \right\rangle$$

If $y + e \neq x$ for |e| = 1, this can be iterated. More precisely, it can be iterated |x - y| times and the terms generated can be estimated by (5):

$$\langle |G_{\omega}(x, y; z)|^{s} \rangle \leq (c^{-1} \|\rho\|_{\infty}^{s})^{|x-y|} \sum_{i=1}^{(2d)^{|x-y|}} \langle |G_{\omega}(x, y^{(i)}; z)|^{s} \rangle$$

$$\leq (2dc^{-1} \|\rho\|_{\infty}^{s})^{|x-y|} C \|\rho\|_{\infty}^{s} = C \|\rho\|_{\infty}^{s} e^{-m \|x-y|}$$

with $e^{-m} = 2dc^{-1} \|\rho\|_{\infty}^s$. If $\|\rho\|_{\infty}$ is small enough, we have m > 0.

Proof of Lemma 3. We consider the Hamiltonian⁽¹¹⁾ obtained from h_{ω} by wiggling the potential at x, namely

$$h_{\omega,\kappa} = h_{\omega} + \kappa P_x = h_{\omega + \kappa \delta_x}$$

The space $\Omega \times \mathbb{R} \ni (\omega, \kappa)$ is given the probability measure $d\tilde{P}(\omega, \kappa) = \rho(v_x + \kappa) d\kappa dP(\omega)$. As a result expectations related to h_{ω} and to $h_{\omega,\kappa}$ are the same. That is, for any *P*-measurable function f on Ω

$$\int dP(\omega) f(\omega) = \int d\tilde{P}(\omega, \kappa) f(\omega + \kappa \delta_x)$$
(14)

By the resolvent identity $(h_{\omega} - z)^{-1} = [1 + \kappa (h_{\omega} - z)^{-1} P_x](h_{\omega,\kappa} - z)^{-1}$ we have

$$G_{\omega,\kappa}(x, y; z) = \frac{G_{\omega}(x, y; z)}{1 + \kappa G_{\omega}(x, x; z)} = \frac{1}{\kappa + G_{\omega}(x, x; z)^{-1}} \cdot \frac{G_{\omega}(x, y; z)}{G_{\omega}(x, x; z)}$$

for all $y \in \mathbb{Z}^d$. In particular, since $|G_{\omega,\kappa}(x, x; z)| \leq |\text{Im } z|^{-1}$ for all $\kappa \in \mathbb{R}$ we have $|\text{Im } G_{\omega}(x, x; z)^{-1}| \geq |\text{Im } z|$. Thus

$$|\operatorname{Im} z| \cdot |G_{\omega,\kappa}(x, y; z)|^{2} \leq \frac{|\operatorname{Im} G_{\omega}(x, x; z)^{-1}|}{|\kappa + G_{\omega}(x, x; z)^{-1}|^{2}} \cdot \frac{|G_{\omega}(x, y; z)|^{2}}{|G_{\omega}(x, x; z)|^{2}}$$

On the other hand, we also have

$$\begin{split} |\operatorname{Im} z| \cdot |G_{\omega,\kappa}(x, y; z)|^2 &\leq |\operatorname{Im} z| \sum_{y' \in \mathbb{Z}^d} |G_{\omega,\kappa}(x, y'; z)|^2 \\ &= |\operatorname{Im} z| \left(\delta_x, (h_{\omega,\kappa} - z)^{-1} (h_{\omega,\kappa} - \bar{z})^{-1} \delta_x \right) \\ &= |\operatorname{Im} G_{\omega,\kappa}(x, x; z)| = \frac{|\operatorname{Im} G_{\omega}(x, x; z)^{-1}|}{|\kappa + G_{\omega}(x, x; z)^{-1}|^2} \end{split}$$

Let 0 < s < 1. Using that $\min(1, t^2) \le t^s$ for $t \ge 0$, we combine the above two estimates as

$$|\operatorname{Im} z| \cdot |G_{\omega,\kappa}(x, y; z)|^{2} \leq \frac{|\operatorname{Im} G_{\omega}(x, x; z)^{-1}|}{|\kappa + G_{\omega}(x, x; z)^{-1}|^{2}} \cdot \frac{|G_{\omega}(x, y; z)|^{s}}{|G_{\omega}(x, x; z)|^{s}}$$

We then claim that

$$\sup_{\substack{w \in \mathbb{C} \\ v_x \in \text{supp } \rho}} |\text{Im } w| \cdot |w|^s \int d\kappa \, \rho(v_x + \kappa) \frac{1}{|\kappa + w|^2} < +\infty$$
(15)

.

so that upon using (14) and (3) we obtain

$$|\operatorname{Im} z| \langle |G_{\omega}(x, y; z)|^2 \rangle \leq \operatorname{const} \cdot \langle |G_{\omega}(x, y; z)|^s \rangle \leq \operatorname{const} \cdot e^{-m|x-y|}$$

To prove (15) we note that by $|w|^s \leq |\kappa|^s + |\kappa + w|^s$ we need to estimate

$$|\operatorname{Im} w| \int d\kappa \, \rho(v_x + \kappa) \, |\kappa|^s \frac{1}{|\kappa + w|^2} \\ \leqslant \pi \, \| \, |\kappa|^s \, \rho(v_x + \kappa) \|_{\infty} \leqslant \pi(|v_x|^s \, \|\rho\|_{\infty} + \| \, |\lambda|^s \, \rho(\lambda) \|_{\infty})$$

and

$$|\operatorname{Im} w| \int d\kappa \, \rho(v_x + \kappa) \, \frac{1}{|\kappa + w|^{2-s}} \\ \leq \min(|\operatorname{Im} w|^{-(1-s)}, \operatorname{const} \cdot \|\rho\|_{\infty} \, |\operatorname{Im} w|^s) = \operatorname{const} \cdot \|\rho\|_{\infty}^{1-s} \quad \blacksquare$$

Proof of Theorem 1. We first prove (1). By Wiener's theorem (see, e.g., ref. 3) we have for any states φ, ψ

$$\lim_{t \to \infty} \frac{1}{t} \int_0^t ds \, |(\varphi, e^{-ihs}\psi)|^2 = \sum_{\lambda \in \mathbb{R}} \, |(\varphi, E(\{\lambda\})\psi)|^2$$

where $E(\cdot)$ is the projection-valued measure associated with *h*. Using $P_{|x| < R} = \sum_{|x| < R} \delta_x(\delta_x, \cdot)$, this yields

$$\lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} ds \|P_{|x| \ge R} e^{-ihs} \psi\|^{2}$$

$$= \|\psi\|^{2} - \lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} ds \|P_{|x| < R} e^{-ihs} \psi\|^{2}$$

$$= \|\psi\|^{2} - \sum_{\lambda \in \mathbb{R}} \|P_{|x| < R} E(\{\lambda\})\psi\|^{2}$$

$$= \|E_{c}\psi\|^{2} + \sum_{\lambda \in \mathbb{R}} \left[\|E(\{\lambda\})\psi\|^{2} - \|P_{|x| < R} E(\{\lambda\})\psi\|^{2}\right]$$

$$= \|E_{c}\psi\|^{2} + \sum_{\lambda \in \mathbb{R}} \|P_{|x| \ge R} E(\{\lambda\})\psi\|^{2}$$

from which (1) follows. This in turn implies (2) by means of an Abelian limit and of Parseval's identity. If $I \subset \mathbb{R}$ is a compact set containing the spectrum $\sigma(h)$ in its interior, we have

$$\varepsilon \int_{\mathbb{R}\setminus I} dE \|P_{|x| \ge R} (h - E - i\varepsilon)^{-1} \psi\|^{2}$$

$$\leq \varepsilon \int_{\mathbb{R}\setminus I} dE \|(h - E - i\varepsilon)^{-1} \psi\|^{2}$$

$$\leq \varepsilon \|\psi\|^{2} \sup_{\lambda \in \sigma(h)} \int_{\mathbb{R}\setminus I} dE |\lambda - E - i\varepsilon|^{-2} \xrightarrow{\varepsilon \downarrow 0} 0$$

Since $||\Delta|| \leq 2d$ we have $\sigma(h_{\omega}) \subset [-2d, 2d] + \operatorname{supp} \rho \subset I$ for some fixed compact *I*, with probability 1. Hence

$$\|E_{\omega,\varepsilon}\delta_0\|^2 = \lim_{R \to \infty} \lim_{\varepsilon \downarrow 0} \frac{\varepsilon}{\pi} \int_I dE \|P_{|x| \ge R} (h_\omega - E - i\varepsilon)^{-1} \delta_0\|^2$$
$$= \lim_{R \to \infty} \lim_{\varepsilon \downarrow 0} \frac{\varepsilon}{\pi} \int_I dE \sum_{|x| \ge R} |G_{\omega}(x,0;E+i\varepsilon)|^2$$

almost surely. By Fatou's lemma and (4) we conclude

$$\langle \|E_{\omega,c}\delta_0\|^2 \rangle \leq \lim_{R \to \infty} \lim_{\varepsilon \downarrow 0} \frac{\varepsilon}{\pi} \int_I dE \sum_{|x| \ge R} \langle |G_{\omega}(x,0;E+i\varepsilon)|^2 \rangle$$
$$\leq \frac{C|I|}{\pi} \lim_{R \to \infty} \sum_{|x| \ge R} e^{-m|x|} = 0$$

Similarly, $E_{\omega,c}\delta_x = 0$ almost surely for any $x \in \mathbb{Z}^d$, i.e., $E_{\omega,c} = 0$.

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