# Anderson Localization and the Space-Time Characteristic of Continuum States 

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A proof of Anderson localization is obtained by ruling out any continuous spectrum on the basis of the space-time characteristic of its states.

KEY WORDS: Anderson localization.

## 1. INTRODUCTION AND RESULTS

By now many proofs ${ }^{(1,4,5,11)}$ of localization for the $d$-dimensional Anderson model have been given. Common to all of them, as to this one, is the derivation of some form of exponential decay ${ }^{(8)}$ of the Green's function. In a second step, localization, i.e., absence of continuous spectrum, is then obtained either ${ }^{(1,4,11)}$ using results about the behavior of the spectral measure under rank-one perturbations, or ${ }^{(4,5.7)}$ using that the set of generalized eigenvalues has full spectral measure. The purpose of this paper is to show that this step can be done using a characterization of the continuous spectrum due to Ruelle ${ }^{(10)}$ and Amrein and Georgescu. ${ }^{(2.6)}$ Such a possibility has been conjectured in ref. 8. For the one-dimensional model it has been used in refs. 3 and 9.

We consider just the simplest case. This is the discrete Schrödinger operator

$$
h_{\omega}=-\Delta+v_{\omega}
$$

acting on $l^{2}\left(\mathbb{Z}^{d}\right)$, where $\Delta$ is the discrete Laplacian

$$
(\Delta \psi)(x)=\sum_{|\epsilon|=1} \psi(x+e)
$$

[^0]and $v_{w}$ is a random potential
$$
\left(v_{\omega} \psi\right)(x)=v_{x} \psi(x)
$$

Here $|x|=\sum_{i=1}^{d}\left|x_{i}\right|$ and $\omega=\left\{v_{x}\right\}_{x \in \mathbb{Z}^{d}}$ is a collection of independent identically distributed random variables. We shall assume that the single-site probability distribution has a density $\rho \in L^{1}(\mathbb{R}),\|\rho\|_{1}=1$, with respect to Lebesgue measure. In other words, the probability space $\Omega=\mathrm{X}_{x \in \mathbb{Z}^{d}} \mathbb{P}$ is equipped with the probability measure $d P(\omega)=\prod_{x \in \mathbb{Z}^{d}} \rho\left(v_{x}\right) d v_{x}$.

The strength of the disorder is measured by $\|\rho\|_{x^{-1}}$. Localization occurs if the disorder is large enough.

Theorem 1. Let $\rho \in L^{\infty}(\mathbb{R})$ and of compact support. If $\|\rho\|_{x}$ is small enough, then $h_{\omega}$, has only pure point spectrum with probability 1.

Ruelle's criterion asserts that states associated with the continuous spectrum leave any compact set in the time mean. More precisely, let $E_{c}$ be the projection onto the continuous spectral subspace of an operator $h$ on $I^{2}\left(\mathbb{Z}^{d}\right)$ and let $P_{|. x| \geqslant R}$ be the projection onto wave functions which vanish in $\left\{x \in \mathbb{Z}^{d}| | x \mid<R\right\}$. Then

$$
\begin{align*}
\left\|E_{s} \psi\right\|^{2} & =\lim _{R \rightarrow \infty} \lim _{t \rightarrow \infty} \frac{1}{t} \int_{0}^{t} d s\left\|P_{|\cdot x| \geqslant R} e^{-i h s} \psi\right\|^{2}  \tag{1}\\
& =\lim _{R \rightarrow \infty} \lim _{\varepsilon!0} 2 \varepsilon \int_{0}^{\infty} d s e^{-2 \varepsilon x}\left\|P_{|\cdot x| \geqslant R} e^{-i h s} \psi\right\|^{2} \\
& =\lim _{R \rightarrow \infty} \lim _{\varepsilon \backslash 0} \frac{\varepsilon}{\pi} \int d E\left\|P_{|x| \geqslant R}(h-E-i \varepsilon)^{-1} \psi\right\|^{2} \tag{2}
\end{align*}
$$

The Green's function consists of matrix elements of the resolvent

$$
G(x, y ; z)=\left(\delta_{x},(h-z)^{-1} \delta_{y}\right)
$$

where the states $\delta_{n}$ are given by $\delta_{n}(m)=\delta_{n m n}\left(n, m \in \mathbb{Z}^{d}\right)$.
Lemma 2. Let $\|\rho\|_{x}$ be small enough and $0<s<1$. Then there are $C, m>0$ such that

$$
\begin{equation*}
\left.\left.\langle | G_{o}(x, y ; z)\right|^{x}\right\rangle \leqslant C e^{-m|x-x|} \tag{3}
\end{equation*}
$$

for all $z \in \mathbb{C} \backslash \mathbb{R}, x, y \in \mathbb{Z}^{d}$.
Here $\langle\cdot\rangle$ denotes the expectation with respect to the probability measure. In ref. 1 a similar estimate was obtained. There the Green's function is regularized by going to finite volumes; here, by going to complex energies.

We then extend the result to higher moments of the Green's function. Specifically:

Lemma 3. Let $\rho$ be as in Lemma 2 and, in addition, of compact support. Then there are $C, m>0$ such that

$$
\begin{equation*}
\left.\left.|\operatorname{Im} z|\langle | G_{\omega}(x, y ; z)\right|^{2}\right\rangle \leqslant C e^{-m|x-y|} \tag{4}
\end{equation*}
$$

for all $z \in \mathbb{C} \backslash \mathbb{R}, x, y \in \mathbb{Z}^{d}$.
Note that the moment of the Green's function in (3) stays bounded as z approaches the real axis, whereas in (4) it may diverge like $|\operatorname{Im}=|^{-1}$. Setting $z=E+i \varepsilon$, we shall see that (4) controls the expectation of (2).

The conductivity tensor as defined by the Kubo-Greenwood formula ${ }^{(8)}$ is

$$
\left.\sigma_{i j}(E)=\left.\lim _{\varepsilon \not 0} \frac{\varepsilon^{2}}{\pi} \sum_{x \in \mathbb{Z}^{d}} x_{i} x_{j}\langle | G_{\iota \omega}(0, x ; E+i \varepsilon)\right|^{2}\right\rangle
$$

From (4) we immediately get:

## Corollary 4:

$$
\sigma_{i j}(E)=0
$$

## 2. PROOFS

We follow ref. 1 quite closely and begin with:
Lemma 5. Let $0<s<1$. Then there is $C>0$ such that

$$
\begin{equation*}
\left.\left.\langle | G_{\omega}(x, y ; z)\right|^{\cdot}\right\rangle \leqslant C\|\rho\|_{x}^{s} \tag{5}
\end{equation*}
$$

for all $z \in \mathbb{C} \backslash \mathbb{R}, x, y \in \mathbb{Z}^{d}$.
Proof. We assume $x \neq y$, the case $x=y$ being similar but easier. The dependence of $G_{\omega}(x, y ; z)$ on $v_{x}, v_{y}$ (at fixed values of the potential elsewhere) is particularly simple. To exhibit it, one writes

$$
h_{c o}=h_{c o}+v_{x} P_{x}+v_{y} P_{y}
$$

where $\hat{\omega}$ is obtained from $\omega$ by setting $v_{x}=v_{r}=0$, and $P_{n}=\delta_{n}\left(\delta_{n}, \cdot\right)$ are the projections on the states $\delta_{n}$. Note that $h_{10}$ differs from $h_{i j}$ by a rank-2 perturbation acting on the range of $P=P_{x}+P_{y}$. From the second resolvent identity $\left(h_{\dot{\omega}}-z\right)^{-1}=\left[1+\left(h_{\dot{\omega}}-z\right)^{-1}\left(v_{x} P_{x}+v_{y} P_{y}\right)\right]\left(h_{\omega}-z\right)^{-1}$ we obtain an identity on Ran $P$ known as Krein's formula:

$$
\begin{equation*}
P\left(h_{\omega}-z\right)^{-1} P=\left(A+v_{x} P_{x}+v_{y} P_{y}\right)^{-1} \tag{6}
\end{equation*}
$$

where $A=\left[P\left(h_{\dot{\omega}}-z\right)^{-1} P\right]^{-1}$, provided it exists, acts on $\operatorname{Ran} P$ and is independent of $v_{x}, v_{y}$. It indeed exists for $z \in \mathbb{C} \backslash \mathbb{R}$ because $(\operatorname{Im} z)^{-1}$ $\operatorname{Im}\left(h_{\dot{\omega}}-z\right)^{-1}=\left(h_{\dot{\omega}}-\bar{z}\right)^{-1}\left(h_{\dot{\omega}}-z\right)^{-1}$ is positive definite. In particular,

$$
-\frac{\operatorname{Im} A}{\operatorname{Im} z}=\frac{1}{\operatorname{Im} z} \frac{A^{*}-A}{2 i}=A^{*} P \frac{\operatorname{Im}\left(h_{i \dot{u}}-z\right)^{-1}}{\operatorname{Im} z} P A
$$

is positive definite, too. Using matrix notation with respect to the basis $\left\{\delta_{x}, \delta_{y}\right\}$,

$$
A=\left(\begin{array}{ll}
a_{x x} & a_{x y} \\
a_{y x} & a_{y y}
\end{array}\right), \quad \operatorname{Im} A=\left(\begin{array}{cc}
\operatorname{Im} a_{x x} & (1 / 2 i)\left(a_{x y}-\overline{a_{y x}}\right) \\
(1 / 2 i)\left(a_{y x}-\overline{a_{x y}}\right) & \operatorname{Im} a_{y y}
\end{array}\right)
$$

we thus have from (6)

$$
\begin{equation*}
G_{\omega}(x, y ; z)=-\frac{a_{x y}}{\left(v_{x}+a_{x x}\right)\left(v_{y}+a_{y y}\right)-a_{x y} a_{y x}} \tag{7}
\end{equation*}
$$

By retaining only the real, resp. the imaginary part of the denominator, we get

$$
\begin{aligned}
& \left|G_{t y}(x, y ; z)\right| \leqslant \frac{\left|a_{x y}\right|}{\left|u_{x} u_{y}-\operatorname{Im} a_{x x} \operatorname{Im} a_{y y}-\operatorname{Re}\left(a_{x y} a_{y x}\right)\right|} \\
& \left|G_{v y}(x, y ; z)\right| \leqslant \frac{\left|a_{x y}\right|}{\left|u_{x} \operatorname{Im} a_{y y}+u_{y} \operatorname{Im} a_{x x}-\operatorname{Im}\left(a_{x y} a_{y x}\right)\right|}
\end{aligned}
$$

with $u_{i}=v_{i}+\operatorname{Re} a_{i i}(i=x, y)$. Moreover,

$$
\begin{equation*}
\operatorname{det} \operatorname{Im} A=\operatorname{Im} a_{x x} \operatorname{Im} a_{y y}+\frac{1}{2} \operatorname{Re}\left(a_{x y} a_{y x}\right)-\frac{1}{4}\left(\left|a_{x y}\right|^{2}+\left|a_{y x}\right|^{2}\right)>0 \tag{8}
\end{equation*}
$$

(i) We shall first treat the case where

$$
\begin{equation*}
\max \left(\left|\operatorname{Im} a_{x x}\right|,\left|\operatorname{Im} a_{y y}\right|\right)<\frac{1}{2}\left|a_{x y}\right| \tag{9}
\end{equation*}
$$

Using (8), we then have

$$
\begin{aligned}
c^{2} & =\operatorname{Im} a_{x x} \operatorname{Im} a_{y y}+\operatorname{Re}\left(a_{x y} a_{y x}\right) \\
& >\frac{1}{2}\left(\left|a_{x y}\right|^{2}+\left|a_{y x}\right|^{2}\right)-\operatorname{Im} a_{x x} \operatorname{Im} a_{y y}>\frac{1}{4}\left|a_{x y}\right|^{2}
\end{aligned}
$$

and thus

$$
\left|G_{\omega}(x, y ; z)\right| \leqslant \frac{2 c}{\left|u_{x} u_{y}-c^{2}\right|}=\frac{2 c^{-1}}{\left|c^{-2} u_{x} u_{y}-1\right|}
$$

We note that for any $w_{x}, w_{y} \in \mathbb{R}$

$$
\begin{equation*}
\min \left(\left|w_{x}-f\left(w_{y}\right)\right|,\left|w_{y}-f\left(w_{x}\right)\right|\right) \leqslant\left|w_{x} w_{y}-1\right| \tag{10}
\end{equation*}
$$

where $w f(w)=\min \left(1, w^{2}\right)$. Indeed, if $w_{x}^{2} \geqslant 1$, then

$$
\left|w_{y}-f\left(w_{x}\right)\right|=\left|w_{y}-w_{x}^{-1}\right| \leqslant\left|w_{x} w_{y}-1\right|
$$

and the same argument applies if $w_{y}^{2} \geqslant 1$. If, however, $w_{x}^{2}, w_{y}^{2}<1$, then

$$
\begin{aligned}
{\left[w_{x}-f\left(w_{y}\right)\right]^{2} } & =\left[w_{y}-f\left(w_{x}\right)\right]^{2}=\left(w_{x}-w_{y}\right)^{2} \\
& =\left(w_{x} w_{y}-1\right)^{2}-\left(1-w_{x}^{2}\right)\left(1-w_{y}^{2}\right)<\left(w_{x} w_{y}^{\prime}-1\right)^{2}
\end{aligned}
$$

By (10) we estimate

$$
\left|G_{w}(x, y ; z)\right|^{s} \leqslant 2^{s}\left(\left|u_{x}-c f\left(c^{-1} u_{y}\right)\right|^{-s}+\left|u_{y}-c f\left(c^{-1} u_{x}\right)\right|^{-s}\right)
$$

To estimate its expectation we shall use that

$$
\begin{align*}
\int d v \rho(v)|v-\beta|^{-s} & \leqslant \lambda^{-s} \int_{|v-\beta| \geqslant \lambda} d v \rho(v)+\|\rho\|_{\infty} \int_{|v-\beta|<\lambda} d v|v-\beta|^{-s} \\
& \leqslant \lambda^{-s}\|\rho\|_{1}+\frac{2 \lambda^{1-s}}{1-s}\|\rho\|_{\infty} \leqslant C_{s}\|\rho\|_{1}^{1-s}\|\rho\|_{\infty}^{s} \tag{11}
\end{align*}
$$

with $C_{s}=(2 / s)^{s}(1-s)^{-1}$ after minimizing over $\lambda>0$. (This estimate holds for any $\beta \in \mathbb{C}$ although we use it here for $\beta \in \mathbb{R}$ ). Hence

$$
\int d v_{x} d v_{y} \rho\left(v_{x}\right) \rho\left(v_{y}\right) \mid G_{w}(x, y ; z)\left\|^{s} \leqslant 2 \cdot 2^{s} C_{s}\right\| \rho \|_{\infty}^{s}
$$

(ii) In case (9) fails, we have $\left|\operatorname{Im} a_{i i}\right| \geqslant\left|a_{x y}\right| / 2$ for $i=x$ or $i=y$. We shall consider only $i=y$, the other case being similar. Then

$$
\begin{gathered}
\left|G_{\omega}(x, y ; z)\right| \leqslant \frac{2}{\left|u_{x}+\left[u_{y} \operatorname{Im} a_{x x}-\operatorname{Im}\left(a_{x y} a_{y x}\right)\right]\left(\operatorname{Im} a_{y y}\right)^{-1}\right|} \\
\int d v_{x} d v_{y} \rho\left(v_{x}\right) \rho\left(v_{y}\right)\left|G_{\omega}(x, y ; z)\right|^{s} \leqslant 2^{s} C_{s}\|\rho\|_{\infty}^{s}
\end{gathered}
$$

By joining the results of the two cases, we see that the expectation with respect to $v_{x}, v_{y}$ is bounded uniformly in $\hat{\omega}$.

Similarly, the next tool is a version of the decoupling lemma of ref. 1.
Lemma 6. Let $0<s<1$. Then there is $c>0$ such that

$$
\begin{equation*}
\frac{\int d v \rho(v)\left(|v-\eta|^{s} /|v-\beta|^{s}\right)}{\int d v \rho(v)\left(1 /|v-\beta|^{s}\right)} \geqslant c \frac{\|\rho\|_{1}^{s}}{\|\rho\|_{x}^{s}} \tag{12}
\end{equation*}
$$

for all $\rho \in L^{1}(\mathbb{R}) \cap L^{x}(\mathbb{R}), 0 \not \equiv \rho \geqslant 0$, and all $\beta, \eta \in \mathbb{C}$.
Proof. We may assume $\eta \in \mathbb{R}$ since the integral in the numerator becomes smaller upon replacing $\eta$ by its real part. By translation we may then assume $\eta=0$. Finally, by scaling we may assume $\|\rho\|_{1}=\|\rho\|_{\infty}=1$. We then write $N$ (resp. $D$ ) for the numerator (resp. denominator) of the fraction in (12) and distinguish between the cases (i) $\int_{|v| \geqslant|\beta|} d v \rho(v) \geqslant 1 / 2$ and (ii) $\int_{|r|<|\beta|} d v \rho(v)>1 / 2$.
(i) In this case,

$$
N \geqslant \int_{|r| \geqslant|\beta|} d v \rho(v) \frac{|v|^{s}}{|v-\beta|^{s}} \geqslant 2^{-s} \int_{|r| \geqslant|\beta|} d v \rho(v) \geqslant 2^{-(s+1)}
$$

and $D \leqslant C_{s}$ by (11).
(ii) For any $\lambda>0$

$$
\begin{aligned}
\int_{|r|^{\prime} \leqslant \lambda} d v \rho(v) \frac{1}{|v-\beta|^{s}} & \leqslant \int_{|v| \leqslant \lambda} d v \frac{1}{|v-\beta|^{s}} \\
& \leqslant \min \left(\frac{2 \lambda}{(|\beta|-\lambda)_{+}^{s}}, \frac{2 \lambda^{1-s}}{1-s}\right) \leqslant \text { const } \cdot \lambda|\beta|^{-s}
\end{aligned}
$$

so that

$$
N \geqslant \lambda^{s} \int_{|v|>\lambda} d v \rho(v) \frac{1}{|v-\beta|^{s}} \geqslant \lambda^{s}\left(D-\text { const } \cdot \lambda|\beta|^{-s}\right)
$$

Since

$$
D \geqslant \int_{|v|<|\beta|} d v \rho(v) \frac{1}{|v-\beta|^{*}} \geqslant(2|\beta|)^{-s} \int_{|v|<|\beta|} d v \rho(v)>\frac{1}{2}(2|\beta|)^{-s}
$$

we find $N / D \geqslant \lambda^{s}(1-c \lambda) \geqslant$ const for some constant $c$ and $\lambda=(2 c)^{-1}$.
Proof of Lemma 2. ${ }^{(1)}$ According to (7), we have

$$
\begin{equation*}
G_{\omega}(x, y ; z)=\frac{\alpha}{v_{y}-\beta} \tag{13}
\end{equation*}
$$

where $\alpha, \beta$ depend on $\left\{v_{i}\right\}_{i \neq r}$, but not on $v_{y}$. By taking the $x y$ matrix element of $\left(h_{\omega}-z\right)^{-1}\left(h_{\omega}-z\right)=1$, we obtain for $y \neq x$

$$
\sum_{|e|=1} G_{\omega}(x, y+e ; z)=\left(v_{y}-z\right) G_{\omega}(x, y ; z)
$$

and hence

$$
\sum_{|e|=1}\left|G_{\omega v}(x, y+e ; z)\right|^{s} \geqslant\left|v_{y}-z\right|^{s}\left|G_{\omega}(x, y ; z)\right|^{s}
$$

We then take expectations using (13), (12),

$$
\begin{aligned}
\left.\left.\left\langle\sum_{|e|=1}\right| G_{\omega}(x, y+e ; z)\right|^{s}\right\rangle & \left.\geqslant\langle | v_{y}-\left.z\right|^{s}\left|G_{\omega}(x, y ; z)\right|^{s}\right\rangle \\
& \left.\geqslant\left. c\|\rho\|_{\infty}^{-s}\langle | G_{\omega}(x, y ; z)\right|^{s}\right\rangle
\end{aligned}
$$

If $y+e \neq x$ for $|e|=1$, this can be iterated. More precisely, it can be iterated $|x-y|$ times and the terms generated can be estimated by (5):

$$
\begin{aligned}
\left.\left.\langle | G_{\omega}(x, y ; z)\right|^{s}\right\rangle & \left.\leqslant\left.\left(c^{-1}\|\rho\|_{x}^{s}\right)^{|x-y|} \sum_{i=1}^{(2 d)^{|x-s|}}\langle | G_{\omega \varphi}\left(x, y^{(i)} ; z\right)\right|^{s}\right\rangle \\
& \leqslant\left(2 d c^{-1}\|\rho\|_{x}^{s}\right)^{|x-y|} C\|\rho\|_{\infty}^{s}=C\|\rho\|_{\infty}^{s} e^{-m|x-y|}
\end{aligned}
$$

with $e^{-m}=2 d c^{-1}\|\rho\|_{\infty}^{s}$. If $\|\rho\|_{\infty}$ is small enough, we have $m>0$.
Proof of Lemma 3. We consider the Hamiltonian ${ }^{(t)}$ obtained from $h_{\omega}$ by wiggling the potential at $x$, namely

$$
h_{\omega, \kappa}=h_{(\omega}+\kappa P_{x}=h_{\omega+\kappa \delta_{x}}
$$

The space $\Omega \times \mathbb{R} \ni(\omega, \kappa)$ is given the probability measure $d \widetilde{P}(\omega, \kappa)=$ $\rho\left(v_{x}+\kappa\right) d \kappa d P(\omega)$. As a result expectations related to $h_{\omega}$ and to $h_{\omega, \kappa}$ are the same. That is, for any $P$-measurable function $f$ on $\Omega$

$$
\begin{equation*}
\int d P(\omega) f(\omega)=\int d \tilde{P}(\omega, \kappa) f\left(\omega+\kappa \delta_{x}\right) \tag{14}
\end{equation*}
$$

By the resolvent identity $\left(h_{\omega}-z\right)^{-1}=\left[1+\kappa\left(h_{\omega}-z\right)^{-1} P_{x}\right]\left(h_{\omega, \kappa}-z\right)^{-1}$ we have

$$
G_{\omega, \kappa}(x, y ; z)=\frac{G_{\omega}(x, y ; z)}{1+\kappa G_{\omega}(x, x ; z)}=\frac{1}{\kappa+G_{\omega}(x, x ; z)^{-1}} \cdot \frac{G_{\omega}(x, y ; z)}{G_{\omega}(x, x ; z)}
$$

for all $y \in \mathbb{Z}^{d}$. In particular, since $\left|G_{\omega, \kappa}(x, x ; z)\right| \leqslant|\operatorname{Im} z|^{-1}$ for all $\kappa \in \mathbb{R}$ we have $\left|\operatorname{Im} G_{\omega}(x, x ; z)^{-1}\right| \geqslant|\operatorname{Im} z|$. Thus

$$
|\operatorname{Im} z| \cdot\left|G_{\omega, \kappa}(x, y ; z)\right|^{2} \leqslant \frac{\left|\operatorname{Im} G_{\omega}(x, x ; z)^{-1}\right|}{\left|\kappa+G_{\omega}(x, x ; z)^{-1}\right|^{2}} \cdot \frac{\left|G_{\omega}(x, y ; z)\right|^{2}}{\left|G_{\omega}(x, x ; z)\right|^{2}}
$$

On the other hand, we also have

$$
\begin{aligned}
|\operatorname{Im} z| \cdot\left|G_{\omega, \kappa}(x, y ; z)\right|^{2} & \leqslant|\operatorname{Im} z| \sum_{y^{\prime} \in \mathbb{Z}^{d}}\left|G_{\omega, \kappa}\left(x, v^{\prime} ; z\right)\right|^{2} \\
& =|\operatorname{Im} z|\left(\delta_{x},\left(h_{\omega, \kappa}-z\right)^{-1}\left(h_{\omega, \kappa}-\bar{z}\right)^{-1} \delta_{x}\right) \\
& =\left|\operatorname{Im} G_{\omega, \kappa}(x, x ; z)\right|=\frac{\left|\operatorname{Im} G_{\omega}(x, x ; z)^{-1}\right|}{\left|\kappa+G_{\omega}(x, x ; z)^{-1}\right|^{2}}
\end{aligned}
$$

Let $0<s<1$. Using that $\min \left(1, t^{2}\right) \leqslant t^{s}$ for $t \geqslant 0$, we combine the above two estimates as

$$
|\operatorname{Im} z| \cdot\left|G_{\omega, \kappa}(x, y ; z)\right|^{2} \leqslant \frac{\left|\operatorname{Im} G_{\omega}(x, x ; z)^{-1}\right|}{\left|\kappa+G_{\omega}(x, x ; z)^{-1}\right|^{2}} \cdot \frac{\left|G_{\omega}(x, y ; z)\right|^{s}}{\left|G_{\omega}(x, x ; z)\right|^{s}}
$$

We then claim that

$$
\begin{equation*}
\sup _{\substack{w \in \mathbb{C} \\ v_{x} \in \operatorname{supp} \rho}}|\operatorname{Im} w| \cdot|w|^{*} \int d \kappa \rho\left(v_{x}+\kappa\right) \frac{1}{|\kappa+w|^{2}}<+\infty \tag{15}
\end{equation*}
$$

so that upon using (14) and (3) we obtain

$$
\left.\left.\left.|\operatorname{Im} z|\langle | G_{\omega}(x, y ; z)\right|^{2}\right\rangle \leqslant\left.\mathrm{const} \cdot\langle | G_{\omega}(x, y ; z)\right|^{s}\right\rangle \leqslant \mathrm{const} \cdot e^{-m|x-y|}
$$

To prove (15) we note that by $|w|^{s} \leqslant|\kappa|^{s}+|\kappa+w|^{s}$ we need to estimate

$$
\begin{aligned}
& |\operatorname{Im} w| \int d \kappa \rho\left(v_{x}+\kappa\right)|\kappa|^{s} \frac{1}{|\kappa+w|^{2}} \\
& \quad \leqslant \pi\left\||\kappa|^{s} \rho\left(v_{x}+\kappa\right)\right\|_{\infty} \leqslant \pi\left(\left|v_{x}\right|^{s}\|\rho\|_{\infty}+\left\||\lambda|^{s} \rho(\lambda)\right\|_{\infty}\right)
\end{aligned}
$$

and

$$
\begin{aligned}
& |\operatorname{Im} w| \int d \kappa \rho\left(v_{x}+\kappa\right) \frac{1}{|\kappa+w|^{2-s}} \\
& \quad \leqslant \min \left(|\operatorname{Im} w|^{-(1-s)}, \text { const } \cdot\|\rho\|_{\infty}|\operatorname{Im} w|^{s}\right)=\mathrm{const} \cdot\|\rho\|_{\infty}^{1-s}
\end{aligned}
$$

Proof of Theorem 1. We first prove (1). By Wiener's theorem (see, e.g., ref. 3) we have for any states $\varphi, \psi$

$$
\lim _{t \rightarrow \infty} \frac{1}{t} \int_{0}^{t} d s\left|\left(\varphi, e^{-i h s} \psi\right)\right|^{2}=\sum_{i \in \mathbb{R}}|(\varphi, E(\{\lambda\}) \psi)|^{2}
$$

where $E(\cdot)$ is the projection-valued measure associated with $h$. Using $P_{|x|<R}=\sum_{|x|<R} \delta_{x}\left(\delta_{x}, \cdot\right)$, this yields

$$
\begin{aligned}
\lim _{t \rightarrow \infty} & \frac{1}{t} \int_{0}^{t} d s\left\|P_{|x| \geqslant R} e^{-i h s} \psi\right\|^{2} \\
& =\|\psi\|^{2}-\lim _{t \rightarrow \infty} \frac{1}{t} \int_{0}^{t} d s\left\|P_{|x|<R} e^{-i h s s} \psi\right\|^{2} \\
& =\|\psi\|^{2}-\sum_{i \in \mathbb{R}}\left\|P_{|x|<R} E(\{\lambda\}) \psi\right\|^{2} \\
& =\left\|E_{c} \psi\right\|^{2}+\sum_{i \in \mathbb{R}}\left[\|E(\{\lambda\}) \psi\|^{2}-\left\|P_{|x|<R} E(\{\lambda\}) \psi\right\|^{2}\right] \\
& =\left\|E_{c} \psi\right\|^{2}+\sum_{i \in \mathbb{R}}\left\|P_{|x|>R} E(\{\lambda\}) \psi\right\|^{2}
\end{aligned}
$$

from which (1) follows. This in turn implies (2) by means of an Abelian limit and of Parseval's identity. If $I \subset \mathbb{R}$ is a compact set containing the spectrum $\sigma(h)$ in its interior, we have

$$
\begin{aligned}
& \varepsilon \int_{\mathbb{R} \backslash I} d E\left\|P_{|, x| \geqslant R}(h-E-i \varepsilon)^{-1} \psi\right\|^{2} \\
& \quad \leqslant \varepsilon \int_{\mathbb{R} \backslash I} d E\left\|(h-E-i \varepsilon)^{-1} \psi\right\|^{2} \\
& \quad \leqslant \varepsilon\|\psi\|^{2} \sup _{\lambda \in \sigma(h)} \int_{\mathbb{R} \backslash /} d E|\lambda-E-i \varepsilon|^{-2} \underset{\kappa, 0}{ } 0
\end{aligned}
$$

Since $\|\Delta\| \leqslant 2 d$ we have $\sigma\left(h_{\omega}\right) \subset[-2 d, 2 d]+\operatorname{supp} \rho \subset I$ for some fixed compact $I$, with probability 1 . Hence

$$
\begin{aligned}
\left\|E_{\omega, c} \delta_{0}\right\|^{2} & =\lim _{R \rightarrow \infty} \lim _{\varepsilon \downarrow 0} \frac{\varepsilon}{\pi} \int_{,} d E\left\|P_{|. x| \geqslant R}\left(h_{\omega}-E-i \varepsilon\right)^{-1} \delta_{0}\right\|^{2} \\
& =\lim _{R \rightarrow \infty} \lim _{\varepsilon \downarrow 0} \frac{\varepsilon}{\pi} \int_{I} d E \sum_{|x| \geqslant R}\left|G_{\omega}(x, 0 ; E+i \varepsilon)\right|^{2}
\end{aligned}
$$

almost surely. By Fatou's lemma and (4) we conclude

$$
\begin{aligned}
\left\langle\left\|E_{\omega, c} \delta_{0}\right\|^{2}\right\rangle & \left.\leqslant\left.\underline{\lim }_{R \rightarrow \infty} \frac{\lim _{\varepsilon, 0}}{} \frac{\varepsilon}{\pi} \int_{I} d E \sum_{|x| \geqslant R}\langle | G_{\omega}(x, 0 ; E+i \varepsilon)\right|^{2}\right\rangle \\
& \leqslant \frac{C|I|}{\pi} \varliminf_{R \rightarrow \infty} \sum_{|x| \geqslant R} e^{-m|x|}=0
\end{aligned}
$$

Similarly, $E_{\omega, c} \delta_{x}=0$ almost surely for any $x \in \mathbb{Z}^{d}$, i.e., $E_{c, c}=0$.

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